



# **Active Sensor Planning for Multiview Vision Tasks**

Shengyong Chen, Y. F. Li, Jianwei Zhang, Wang Wanliang

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This unique book explores the important issues in studying for active visual perception. The book's eleven chapters draw on recent important work in robot vision over ten years, particularly in the use of new concepts. Implementation examples are provided with theoretical methods for testing in a real robot system. With these optimal sensor planning strategies, this book will give the robot vision system the adaptability needed in many practical applications.



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